

***Flight and Propulsion Control  
Technology Development  
Plans under the new NASA  
Aeronautics Programs***

Irene Gregory

*NASA Langley Research Center*

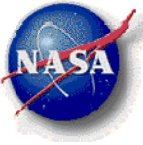
Sanjay Garg

*NASA Glenn Research Center*

SAE Aerospace Control and Guidance  
Systems Committee Meeting

Williamsburg, VA

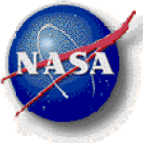
October 11-13, 2006



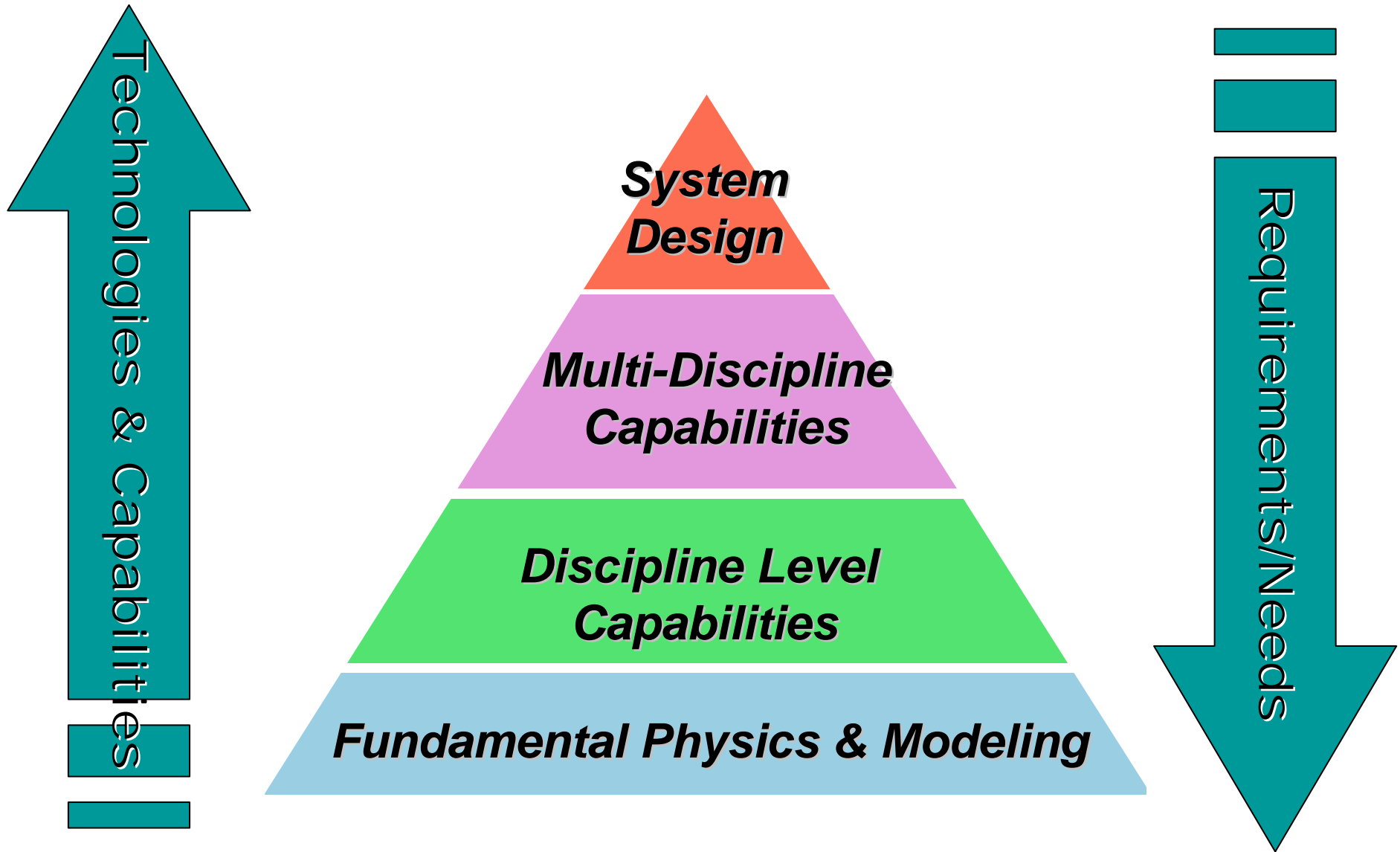
# The Three Principles

---

- NASA is dedicated to the mastery and intellectual stewardship of the core competencies of Aeronautics for the Nation in all flight regimes
- Research will focus in areas that are appropriate to NASA's unique capabilities
- NASA will directly address the needs of the Next Generation Air Transportation System (NGATS) in partnership with the member agencies of the Joint Planning and Development Office (JPDO)



# Research Philosophy





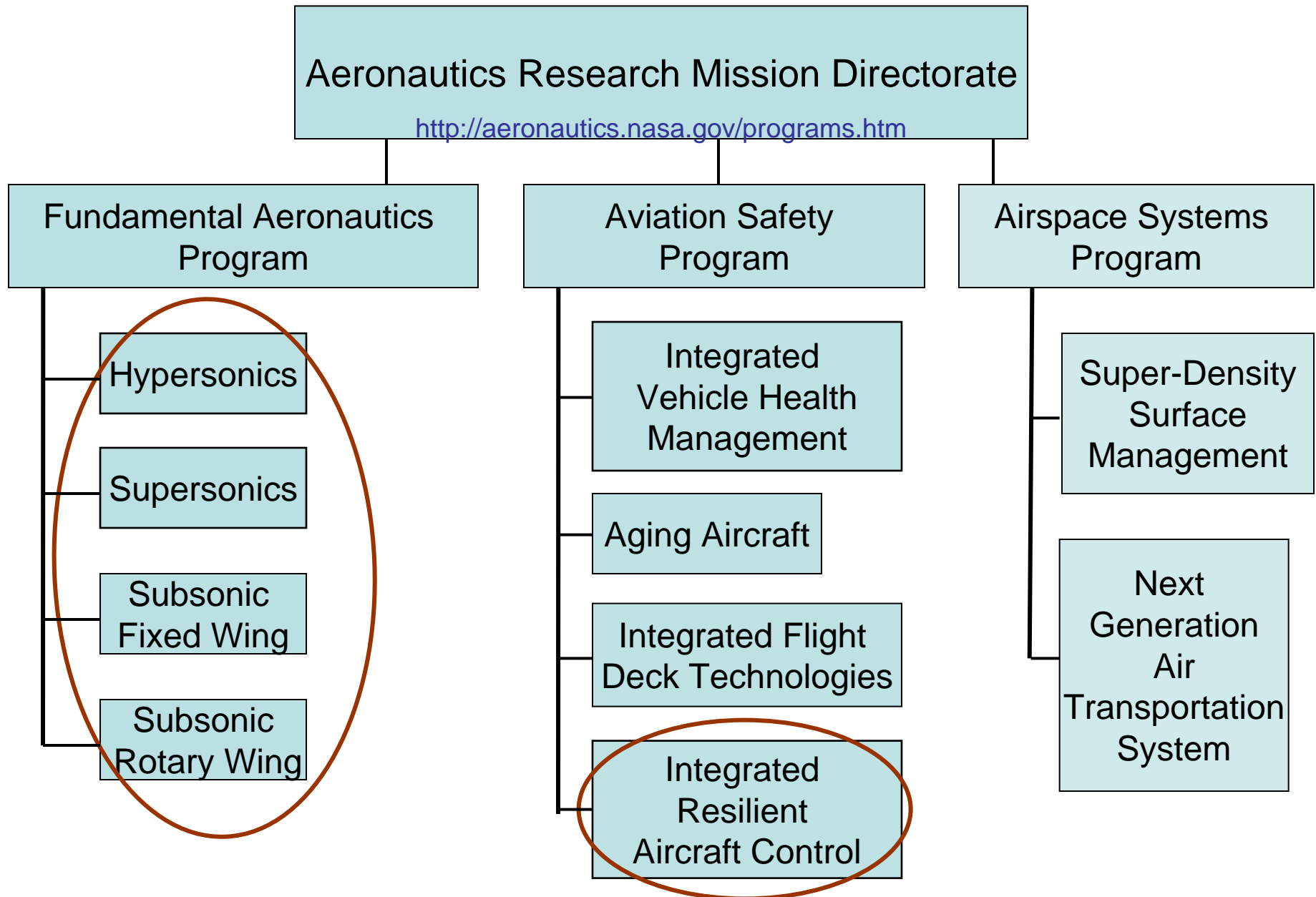
# Impact on Partnerships

---

- NASA will take responsibility for the intellectual stewardship of the core competencies of Aeronautics for the Nation.
  - Ensures the availability of a world class resource (personnel, facilities, knowledge and expertise) ready to be drawn upon by our Government partners (e.g., DoD, FAA, JPDO) and by the private sector.
- University partnerships
  - We will integrate students and faculty as true partners in our research projects.
    - Enables replenishment of workforce at both NASA and in industry.
  - Full and open competition for funds.
- Industry partnerships
  - We will shift from near-term, evolutionary procurements to long-term, intellectual partnerships.
    - Ensures ability to provide long-term, stable investment in capabilities that will benefit all of industry.

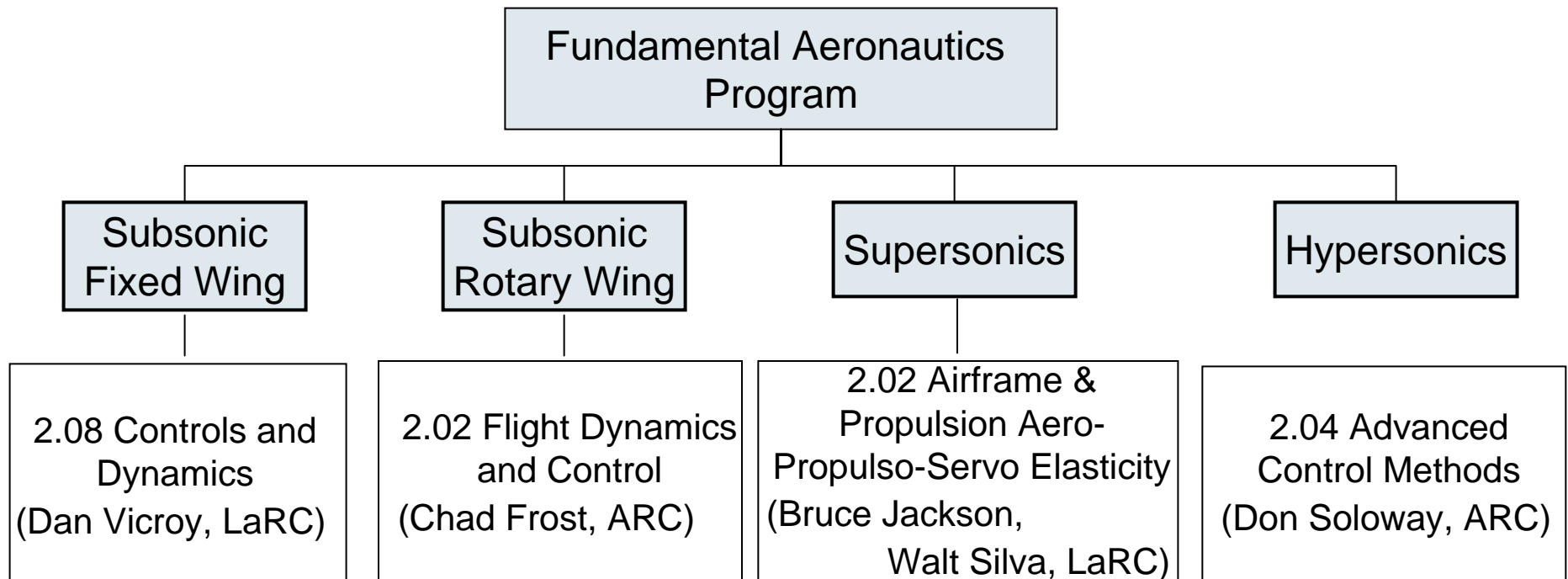


# NASA Aeronautics' Program Structure





# Control Tasks Under Fundamental Aeronautics



- Dynamic modeling and robust control of advanced configurations
- Performance Optimization Control
- Distributed Engine Control
- Advanced control for high lift configurations

- Integrated rotor and transmission control
- Individual blade control to improve HQ and agility
- Pilot performance modeling

- Rapid dynamic model development
- Flexible mode control
- Integrated inlet/engine control
- Active Combustion Control (under different element)

- Guidance and control for multi-mission, multi-propulsion, multi-Mach
- Ground simulations and flight experiment test beds
- General application:
  - Capsule/Reentry Probe
  - Hypersonic Glider
  - Powered Glider

# SFW.2.08 – Controls and Dynamics

## Objective:

Enable improved aircraft performance by developing technologies for robust control of unconventional configurations and active control of components for improved propulsion efficiency and lower emissions.

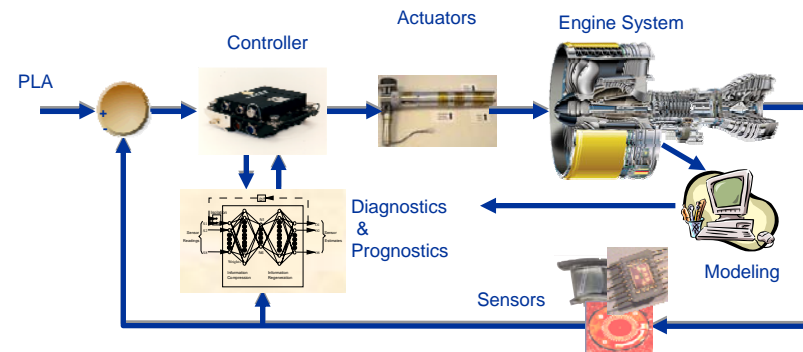
## Approach:

Develop and validate multidisciplinary tools for unsteady, nonlinear flight dynamics, and robust and distributive control technologies.

## Focus:

Foundational and discipline level work in following areas:

- Dynamic modeling and robust control of configurations with distributed and unconventional control effectors
- Performance optimization control
- Distributed engine control
- Advanced control for high lift configurations



*An integrated system perspective is important when developing control system technologies - example engine control.*

## Validation Strategy:

Apply Controls and Dynamics methods to benchmark models and simulations, and test from laboratory to flight:

- Model prediction within uncertainty bounds of test data
- Control approaches provide robustness against uncertainty
- Prototype components meet distributed control requirements

## Highlights of Planned NASA In-House Research:

### Foundational (Level 1):

- Assess aircraft performance optimization control technologies and establish baseline
- Develop methods for modeling control effectiveness of distributed effectors
- Define component requirements for distributed engine control

### Discipline (Level 2):

- Assessment of dynamic modeling methods against existing test data
- Development of robust control approaches for distributed effectors
- Development of performance optimization control methods for unconventional configurations
- Development of advanced control for high lift configurations
- Development of preliminary distributed engine control components

### Multi-Disciplinary and System Integration Work (Level 3 & 4):

- Evaluation of impact of robust control with advanced effectors on overall vehicle performance in flight tests in cooperation with industry partners.
- Quantify impact of distributed control on engine performance and emissions in a high fidelity simulation

### NRA Investment (Level 1 & 2):

#### Potential Phase 1 Research in:

- Uncertainty modeling for robust control development
- Nonlinear control methods
- Test-beds for distributed control architecture and components

### Highlights of Partnership Strategy (Level 3 & 4):

- DoD/DoE - leverage existing models, data, and identify validation opportunities
- NG, LM, Boeing and AFRL - identify dynamic modeling and advanced control validation opportunities on unconventional configurations such as BWB and AMC-X
- GE, P&W - identify opportunities for test of distributed engine control components

# SRW.2.02 – Flight Dynamics and Control

## Objective:

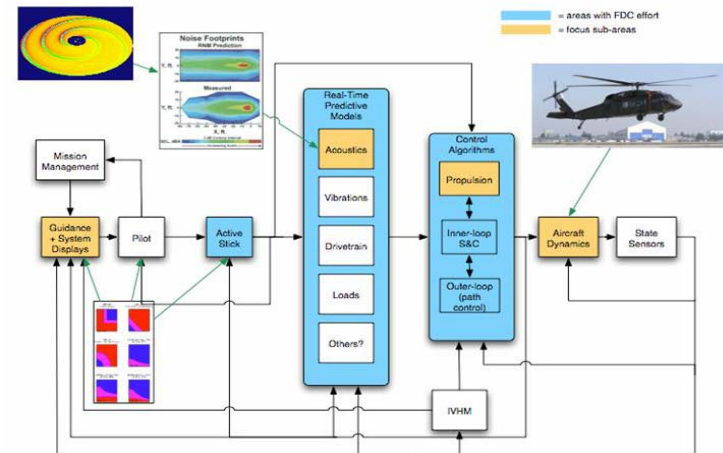
Enable Rotary-Wing aircraft developers to produce products that “Fly as Designed”, with Level 1 Handling Qualities across the flight envelope.

## Approach:

Develop and validate predictive design tools and multi-disciplinary guidance and control algorithms.

## Focus:

- Foundational and discipline level work in following areas:
- Synchronized control of multi-speed rotor, engine and transmission.
  - Exploitation of on-blade and individual-blade control to improve HQ and agility.
  - Pilot performance modeling.



*An integrated aircraft control architecture will incorporate predictive models from multiple disciplines.*

## Validation Strategy:

Evaluate tools, models and techniques from the desktop, through piloted simulation, to flight test, and quantify:

- Model prediction within uncertainty bounds of test data
- Success of robust control methods
- Handling qualities achieved versus predicted

## Highlights of Planned NASA In-House Research:

### Foundational (Level 1):

- Development of multi-speed rotor/engine/transmission-shifting control
- Development of computational pilot performance models that include effects of noise and vibration

### Discipline (Level 2):

- Development of design guidance for control mode transitions
- Development of control optimization strategies for IBC/OBC
- Development of super-integrated vehicle control architecture, incorporating models of acoustics, loads, and vehicle dynamics.

### Multi-Disciplinary and System Integration Work (Level 3 & 4):

- Flight evaluation of super-integrated vehicle control system, utilizing multi-disciplinary predictive models.

## NRA Investment (Level 1 & 2):

### Potential Phase 1 Research in:

- Real-time tip-path-plane measurement
- Enhanced aeroservoelastic mode suppression

## Highlights of Partnership Strategy (Level 3 & 4):

- DoD - leverage existing models, identify validation opportunities, conduct joint development of design tools
- Center for Rotorcraft Innovation (CRI, the Rotorcraft industry consortium) - identify pre-competitive opportunities of mutual interest

## SUP 2.02. Aero-Propulso-ServoElasticity (APSE)

### Objective:

Mitigate the undesirable effects on performance and flying characteristics of highly complex nonlinear aeroelastic/flight dynamics phenomena that simultaneously influence the airframe and propulsion control of unique structural configurations of supersonic aircraft

### Approach:

- ASE/flight dynamic experimental validation data  
Collect high fidelity data on APSE effects using wind tunnel and flight experiments.
- ASE/flight dynamic analysis and design tool development. Assess effectiveness of current analysis tools; initiate development of improved analysis and design tools.
- APSE analysis and design tools. An initial APSE analysis tool set will be defined and integrated.



*Semi span ASE model.*

### Validation Strategy:

Initial validation will be based on completion of tests of an existing semi-span model and on available flight databases. Validation of the APSE analysis tools will require development of a new wind tunnel model with some form of propulsion simulation. Flight data will be valuable for components of the model such as inlets and control surfaces. An industry partner will be sought to infuse configuration design realism into the model development.

# SUP 2.02 APSE

## Highlights of Planned NASA In-House Research:

### Foundational (Level 1):

- Improve airframe non-linear aeroelastic/flight dynamic prediction (body freedom flutter)
- Improve computational efficiency in nonlinear aeroelastic analysis (airframe and engine) through Reduced-Order Modeling techniques
- Rapid flight dynamic model development and related rigid-body control strategies
- Rapid design level analysis and sensitivity analysis

### Discipline (Level 2):

- ASE/flight dynamic and propulsion experimental validation data
- ASE/flight dynamic and propulsion analysis and design tool development
- APSE analysis and design tools

### Multi-Disciplinary and System Integration Work (Level 3 & 4):

- Demonstration of applicability of design tools for safe, comfortable, and efficient supersonic flight

## NRA Investment (Level 1 & 2):

### Potential Phase 1 Research in:

- CFD-based aeroelastic methods development
- Advanced ASE control system design
- Aeroelastic shape sensitivity

## Highlights of Partnership Strategy (Level 3 & 4):

- ✂ DoD computational research opportunities
- ✂ Collaborative work with Industry Consortia for supersonic biz jet

# HYP.2.04 – Advanced Control Methods

## Objective:

Develop next-generation guidance and control algorithms to address the multiple propulsion elements, wide Mach number variation, strong subsystem coupling, and grave modeling uncertainty associated with hypersonic flight; while returning the high performance efficiency necessary for these performance-limited systems.

## Focus:

- Adaptive control
- Numerical optimal control
- Probabilistic modeling and control
- Modeling of system phenomena unique to hypersonic flight, e.g. aerothermoelastic behavior.
- Hierarchical control

## Approach:

Develop technologies leading to design and analysis tools for trajectory design, and design of adaptive guidance and control laws, with particular emphasis on high L/D airbreathing and unpowered vehicles for flight in Earth's atmosphere, and heavy planetary probes with precise landing requirements. Tool development is supplemented by model development and participation in flight experiments.

## Validation Strategy:

- Apply methods to benchmark systems and compare performance to predictions
- Share tools with potential users, e.g. at L4, and get user feedback.

## Highlights of Planned NASA In-House Research:

### Discipline (Level 2):

- Develop algorithms for trajectory shaping and control of future hypersonic vehicles, as well as hierarchical GN&C system architecture.
- Develop by 2009 improved ground simulation capability, with emphasis on simulating performance under various types of uncertainty, system-wide coupling, and associated model uncertainty.
- A Planetary Probe (HMMES-class) drag or roll modulation GN&C experiment will be conducted from the same vehicle. Using the proposed advanced control techniques, the expected >20% improvement in specific GN&C metrics (trajectory mid-point shaping, stability, targeting) can be attained.

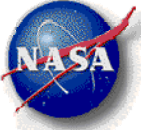
### NRA Investment (Level 1 & 2):

#### Potential Phase 1 Research in:

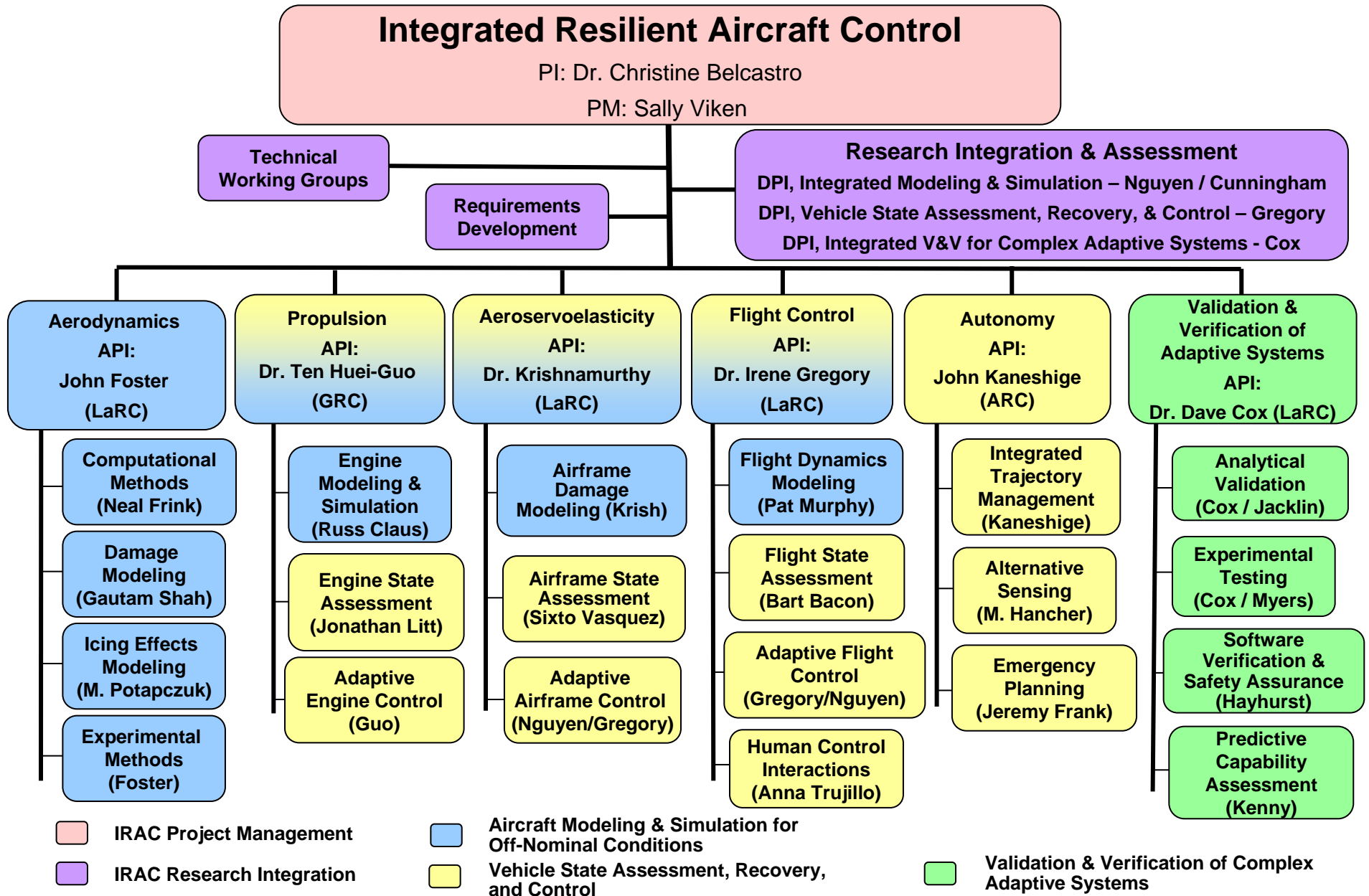
- Adaptive, hierarchical control methods
- Enhanced aeroservoelastic mode suppression

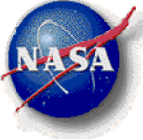
### Highlights of Partnership Strategy (Level 3 & 4):

- DoD - leverage existing (X-43A) and future (X-51 Phoenix) models, identify validation opportunities, conduct joint development of design tools



# IRAC WBS and Research Elements

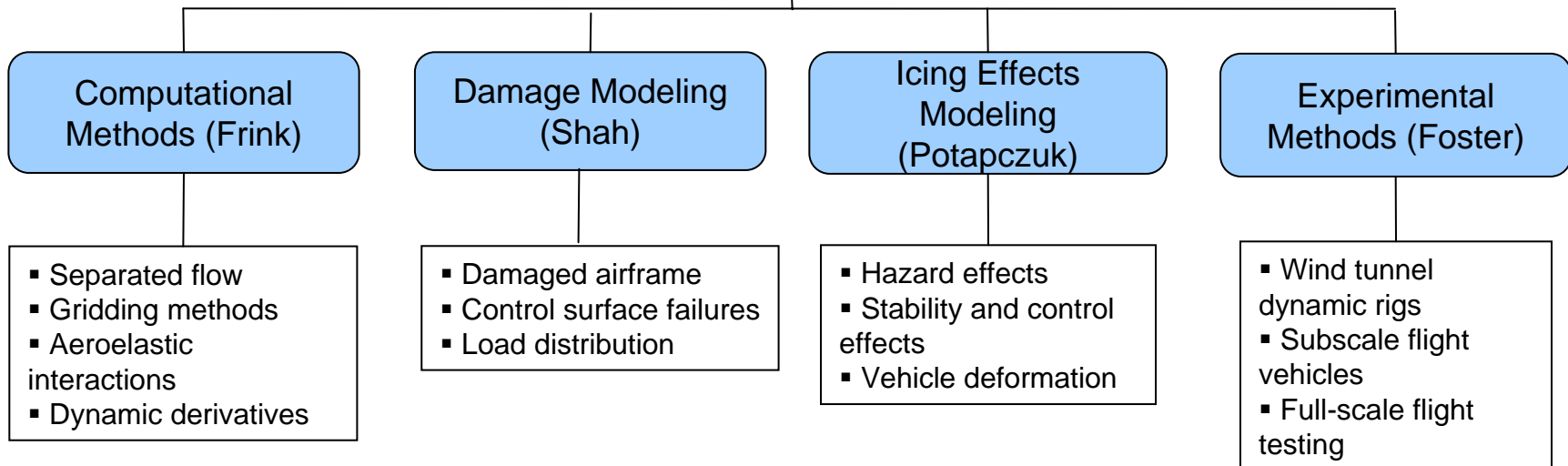




# IRAC Aerodynamics

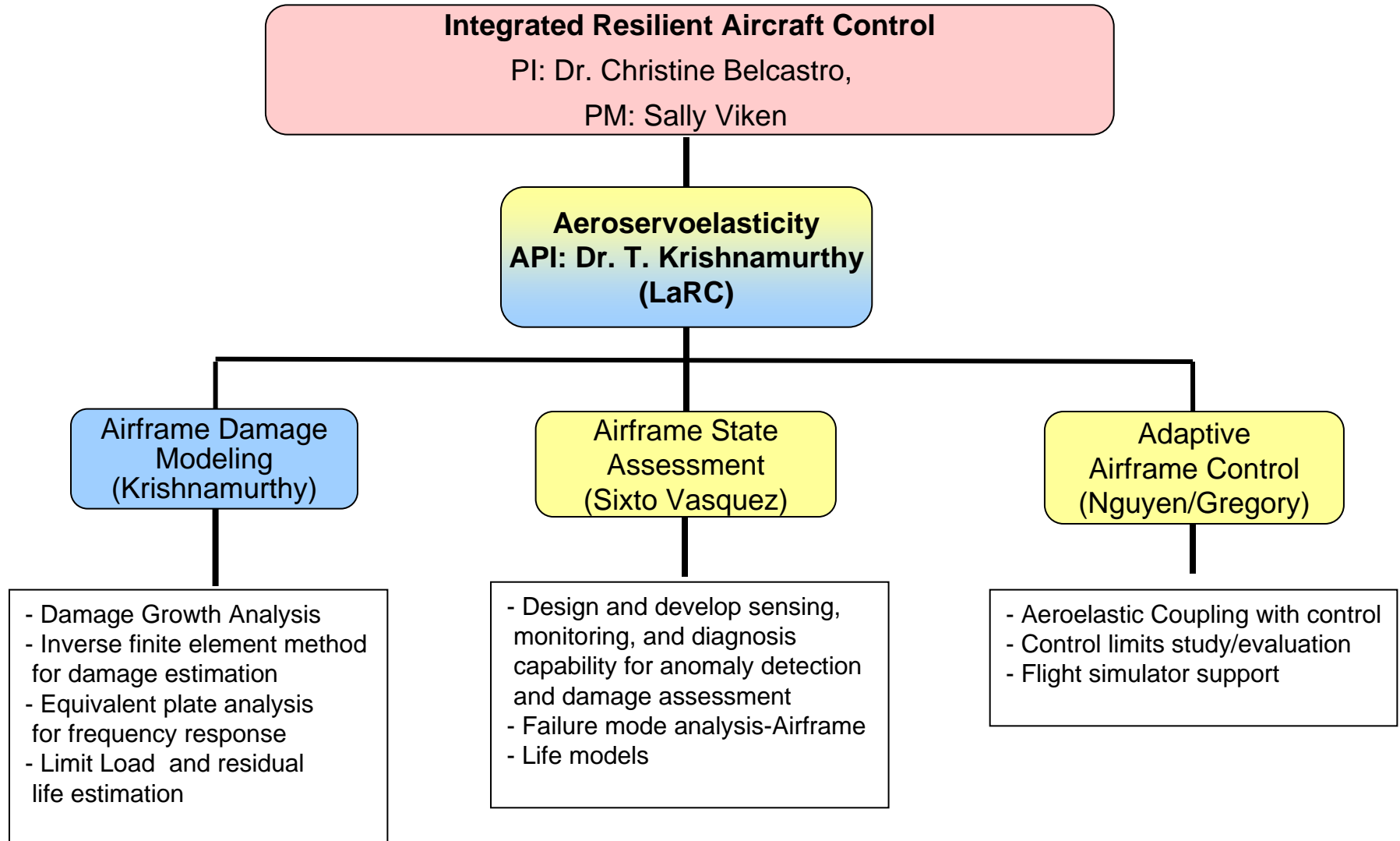
**Integrated Resilient Aircraft Control**  
PI: Dr. Christine Belcastro,  
PM: Sally Viken

**Aerodynamics**  
API: John Foster (LaRC)



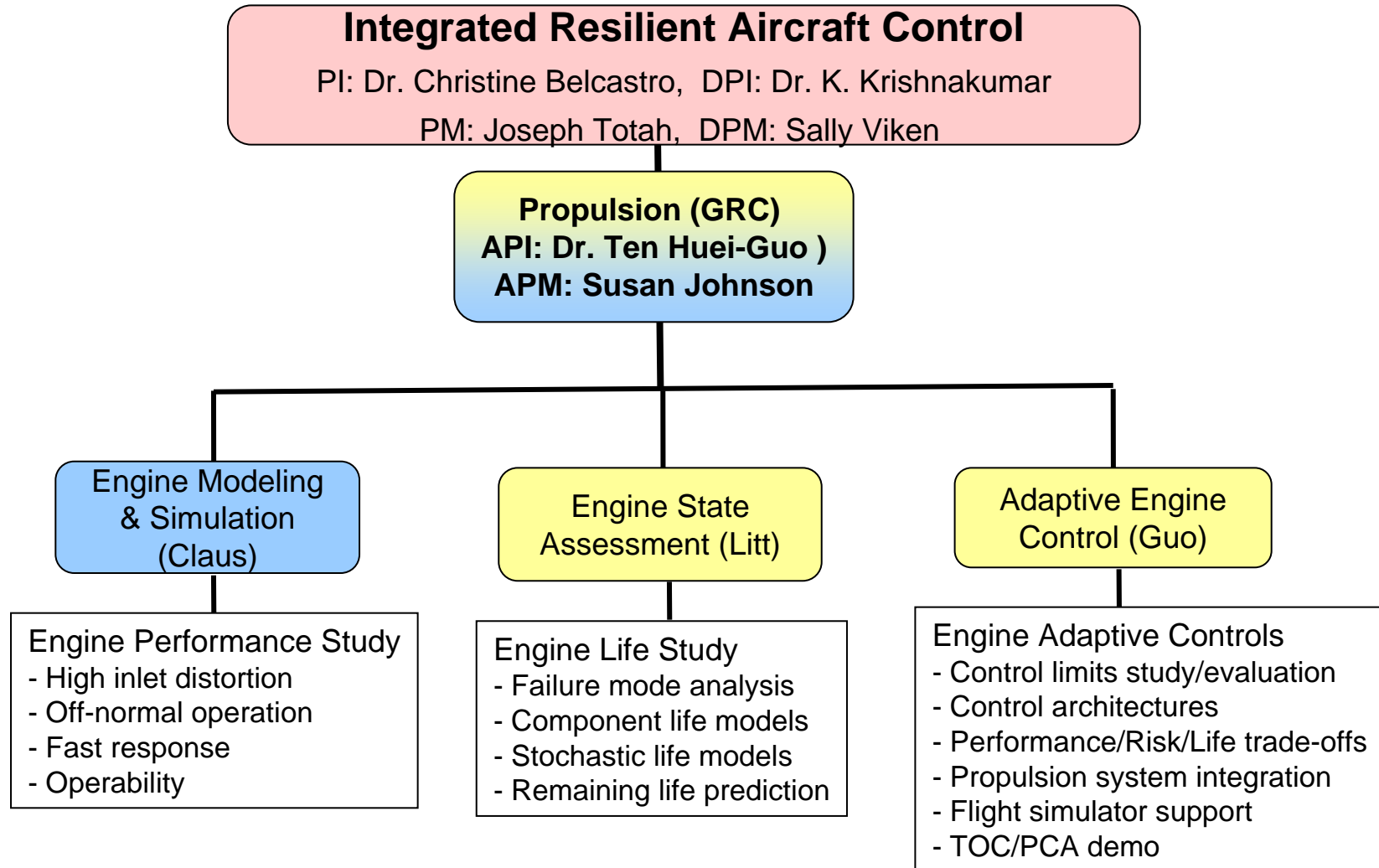


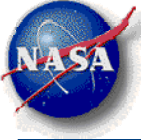
# IRAC Aeroservoelasticity





# IRAC Propulsion





# IRAC Flight controls

## Integrated Resilient Aircraft Control

PI: Dr. Christine Belcastro,  
PM: Sally Viken

### Flight Controls API: Dr. Irene Gregory (LaRC)

#### Flight Dynamics Modeling (Pat Murphy)

- Aircraft response in nonlinear unsteady regimes
- Integrated multidisciplinary and high-fidelity modeling
- Test techniques (ground & flight based), full-scale and sub-scale
- Real-time system identification for damage and aero hazards

#### Flight State Assessment (Bart Bacon)

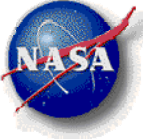
- Safety of Flight Analysis
- Onboard Modeling
  - Achievable Dynamics
  - Flt Envelope Prediction
  - Controllability Prediction
  - Icing Effects Detection
  - Fault Detection Isolation

#### Adaptive Flight Control (Gregory/Nguyen)

- Off-nominal conditions
- multi-objective & multi-constraint control
  - integrated flight/propulsion control
  - variable time scale & dynamic control effector response
  - recovery from upset conditions
  - mitigation of faults and failures
  - composite adaptive control

#### Human Control Interactions (Anna Trujillo)

- Upset, high stress conditions
- functional allocation
  - situational awareness
  - nondeterministic information
  - operator as a sensor



# IRAC Verification and Validation of Adaptive Systems

## Integrated Resilient Aircraft Control

PI: Dr. Christine Belcastro,

PM: Sally Viken

### Verification & Validation of Adaptive Systems API: Dr. Dave Cox (LaRC)

Analytical  
Validation (TBD)

*Robustness and stability of adaptive systems for non-linear, uncertain, and parameter dependent plants*

Experimental  
Capability (Cox)

*Closed-loop subscale flight test capability for damage and upset flight conditions*

Software  
Verification and  
Safety Assurance  
(Hayhurst)

*Correctness of implementation in complex and adaptive software systems*

Predictive  
Capability  
Assessment  
(Kenny)

*Probabilistic techniques for uncertainty quantification and propagation in dynamic models*



# Airborne Subscale Transport Aircraft Research (AirSTAR) Testbed

Aviation Safety: IVHM & IRAC

Technology Verification & Validation



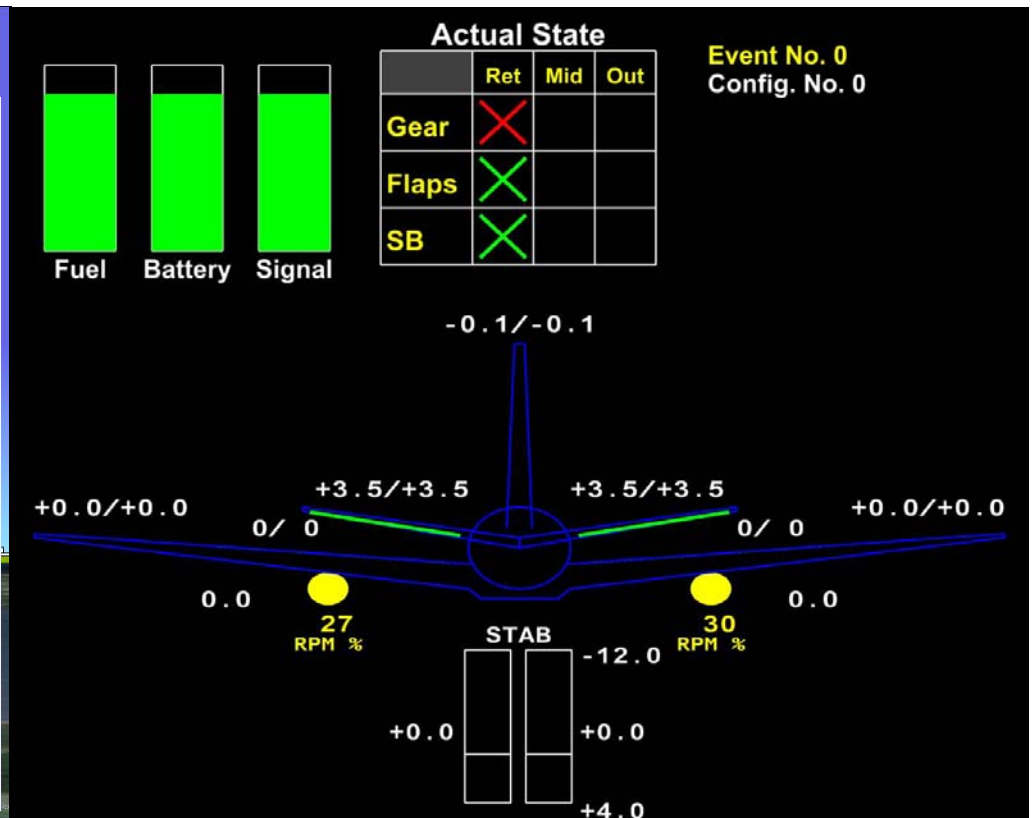
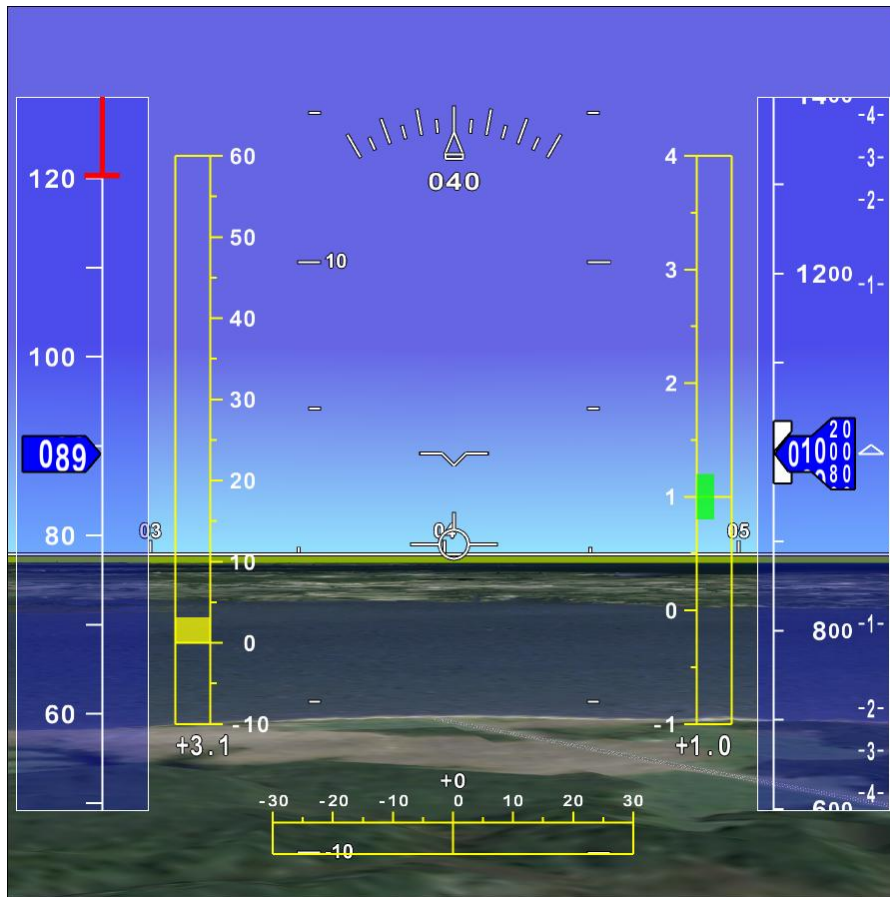


# Subscale Vehicle Flight Testing under Abnormal Conditions

Aviation Safety: IVHM & IRAC

Technology Verification & Validation

- Research pilot station display sample – HUD, vehicle state

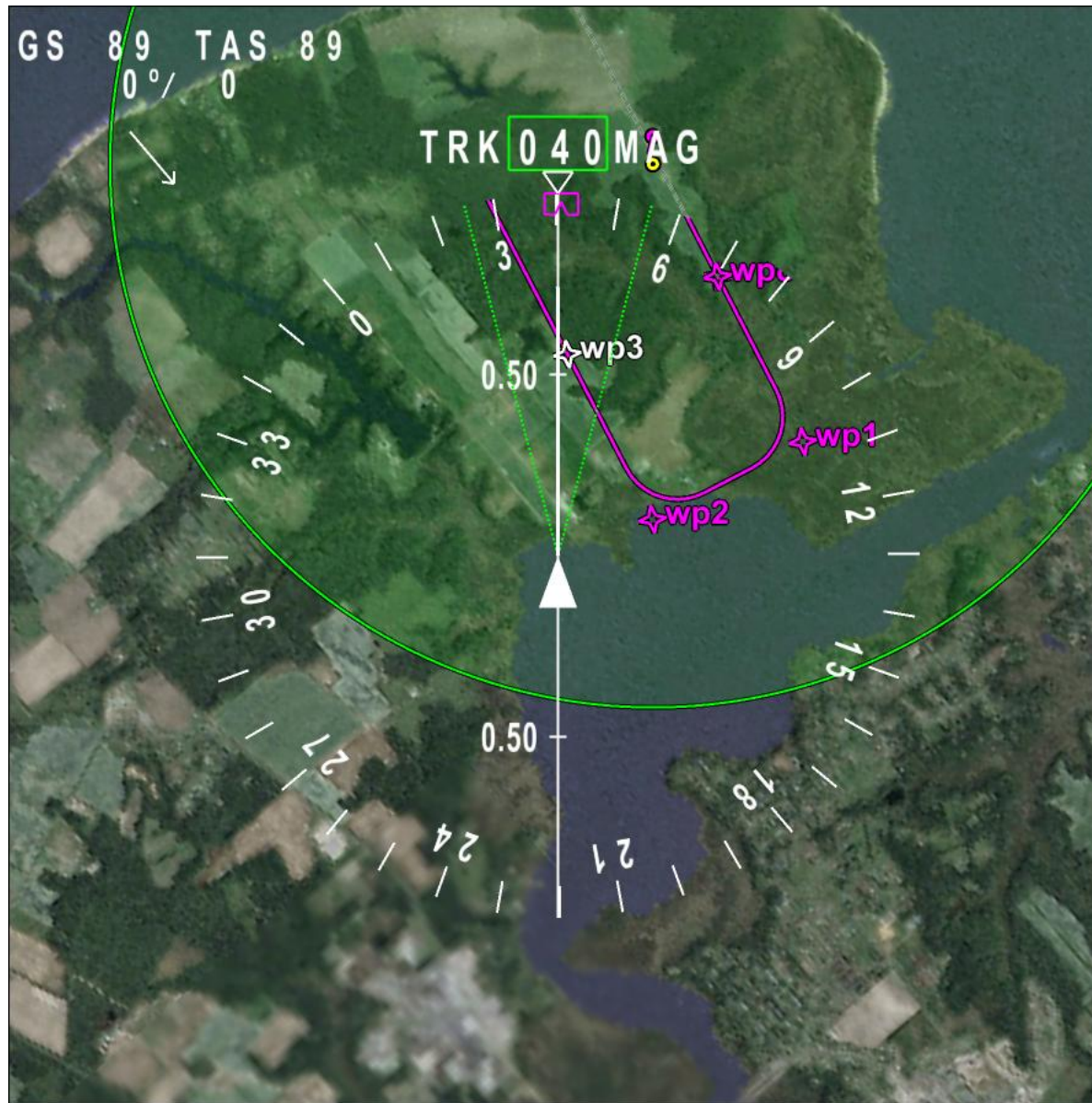




# Research Data Collection Flight Test

Aviation Safety: IVHM & IRAC

Technology Verification & Validation



Flight test area  
and  
flight pattern

**Thank you**

**Questions?**

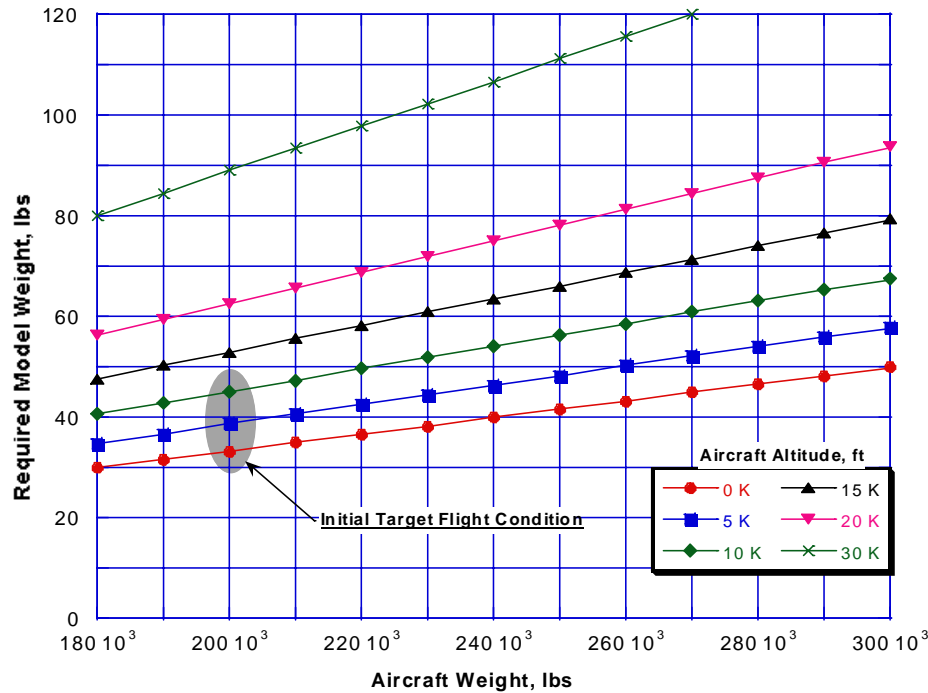


# AirSTAR Generic Transport Model (GTM)

Aviation Safety: IVHM & IRAC

Technology Verification & Validation

## 5.5% Dynamically Scaled Transport Model Aircraft



GTM-T1



GTM-T2

### Selected scaled parameters of a 5.5% model

	Length	Wingspan	Weight	Roll inertia	Airspeed	Altitude
Full Scale Transport	145.5 ft	124 ft	200,000 lbs	2.64e <sup>6</sup> sl-ft <sup>2</sup>	320 mph	13000 ft
5.5% Model	96 in	82 in	49.6 lbs	1.33 sl-ft <sup>2</sup>	75 mph	1000 ft



# Subscale Vehicle Flight Testing under Abnormal Conditions

Aviation Safety: IVHM & IRAC

Technology Verification & Validation

## Airborne Subscale Transport Aircraft Research (AirSTAR) Testbed



### Approach:

- Phased Transport Aircraft Build-Up & Pilot Training
  - » COTS Jet Trainers
  - » Non-Dynamically Scaled Aircraft
  - » Dynamically Scaled Aircraft
- Remote Control via Telemetry
  - » Piloted
  - » Research Algorithms
- Simulation-to-Flight Testing
  - » Pilot Training
  - » Algorithm Implementation & Verification/Validation

### Status & Plans:

- Dynamically Scaled Aircraft: FY02-04
- Subscale Vehicle Simulation: FY03
- Ground/Pilot Station & Ops: FY04-06
- Validation Testing: FY07-11

### Benefits / Payoffs

- In-Flight Validation of Models & Safety/Security Enhancement Systems Involving High-Risk Conditions
  - » Flight Outside of Normal Operational Envelope
  - » Failures / Damage
- In-Flight Testing of Integrated Systems
  - » Vehicle Health Management
  - » Control Upset Prevention & Recovery
  - » Damage Adaptive Control Systems

### Objective: Develop Subscale Vehicle Flight Test Capability for Evaluation & Validation of AvSP Technologies

- Flight Validation of Vehicle Dynamics Modeling for Upset and Damage Conditions
- Failure/Damage Detection & Accommodation
- Upset Recovery

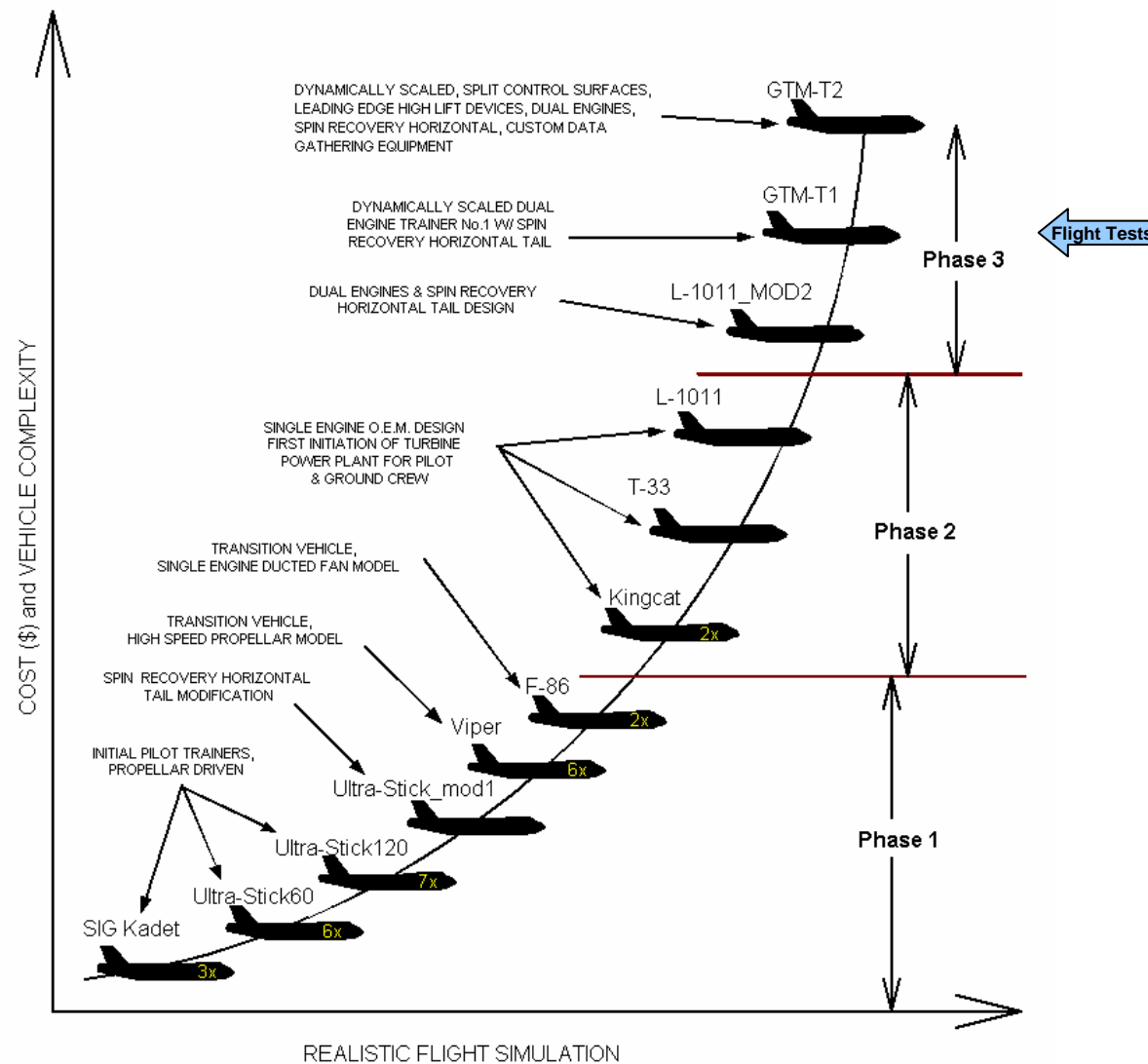


# AirSTAR Pilot Training

Aviation Safety: IVHM & IRAC

Technology Verification & Validation

## Phased Risk Reduction Approach





# AirSTAR Development Schedule

**Aviation Safety: IVHM & IRAC**

**Technology Verification & Validation**

SMITHFIELD

WALLOPS ISLAND

**PHASE I**  
May 2005

**PHASE II**  
May 2006

**PHASE III**  
Sept 2006

**PHASE IV**  
March 2007

**PHASE V**  
Nov 2007



- Dynamically Scaled Vehicle

- Dynamically Scaled Vehicle  
- Data System

- Dynamically Scaled Vehicle  
- Data System

- Dynamically Scaled Vehicle  
- Data System

- Dynamically Scaled Vehicle  
- Data System  
- Autopilot

AIR



- Safety Pilot

- Safety Pilot

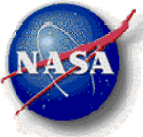
- Safety Pilot  
- Mobile Operations Station

- Safety Pilot  
- Mobile Operations Station  
- Research Pilot (visible range)

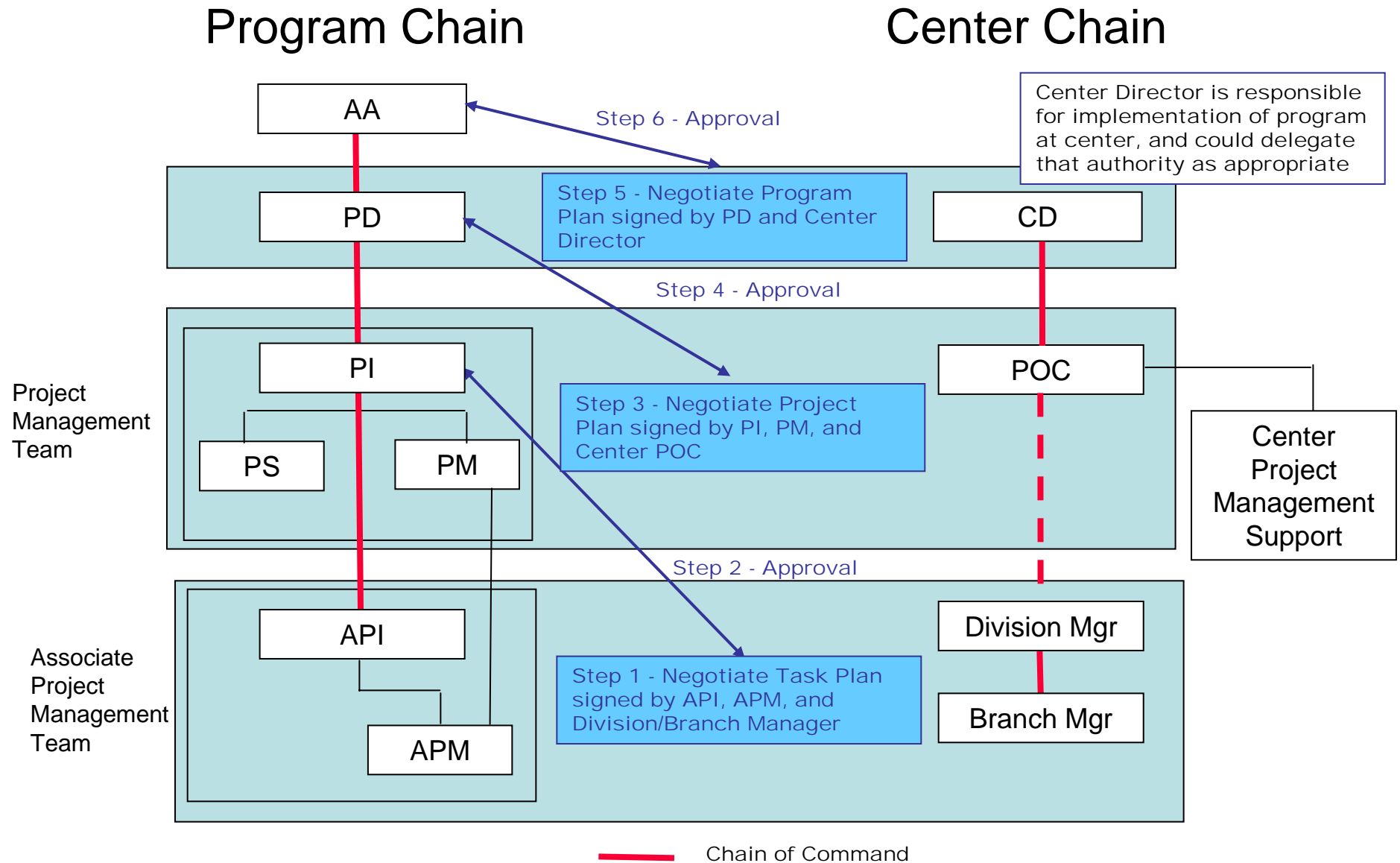
- Safety Pilot  
- Mobile Operations Station  
- Research Pilot  
- Video Tracking (beyond visible range)

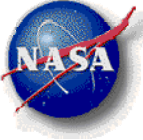
GROUND



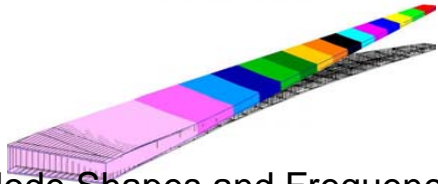


# ARMD Program Management Structure and Working Relationships with Performing Centers

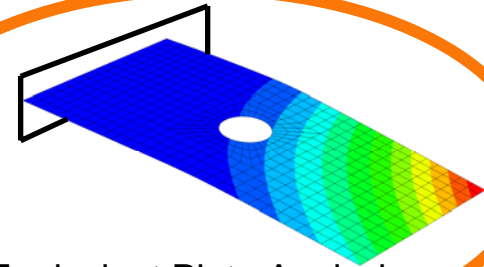




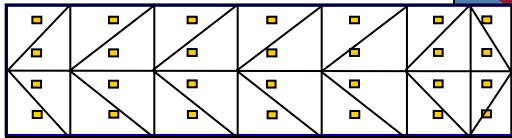
# Airframe Damage Assessment



Mode Shapes and Frequencies of Damaged Wings



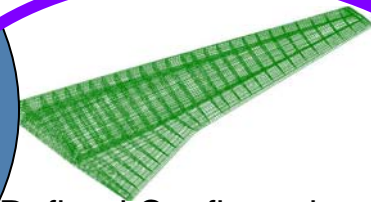
Equivalent Plate Analysis



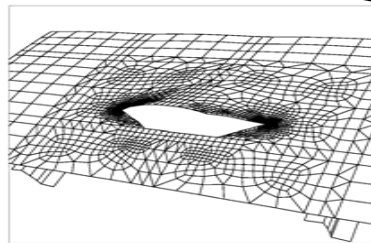
Inverse Finite Element



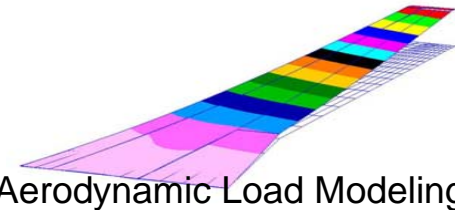
2004 DHL Incident



Refined Configuration Modeling



Damage Growth Analysis



Aerodynamic Load Modeling